

- 1) Time Harmonic Wave Eqn: $\nabla^2 \vec{E}(x,y,z) = -\omega^2 \mu \epsilon \vec{E}(x,y,z)$
 It is also valid for each component of \vec{E} and \vec{H}
- 2) w.l.o.g. assume \vec{E} along \hat{x} direction. Thus $\vec{E} = (E_x(x,y,z), 0, 0)$
- 3) \vec{E} satisfies $\nabla \times \vec{E} = -j\omega \mu \vec{H} \Rightarrow \begin{pmatrix} 0, \frac{\partial E_x}{\partial z}, -\frac{\partial E_x}{\partial y} \end{pmatrix} = -j\omega \mu (H_x, H_y, H_z) \quad \text{--- (1)}$
- | | | |
|-------------------------------|-------------------------------|-------------------------------|
| \hat{x} | \hat{y} | \hat{z} |
| $\frac{\partial}{\partial x}$ | $\frac{\partial}{\partial y}$ | $\frac{\partial}{\partial z}$ |
| E_x | 0 | 0 |
- Obsv #1 $H_x = 0$.

- 4) We wrote E_x as $E_x(x,y,z)$. Several possibilities exist:
- a) $E_x = \text{const.}$ If so, then $\vec{H} = 0$ from (1), but then $\nabla \times \vec{H} = j\omega \epsilon_0 \vec{E}$ gives $\vec{E} = 0$. } Contradiction
 - b) $E_x = E_x(x)$. Same as above $\Rightarrow \vec{H} = 0$. }
 - c) $E_x = E_x(y)$. Leads to $\vec{H} = (0, 0, H_z)$. }
 - d) $E_x = E_x(z)$. Leads to $\vec{H} = (0, H_y, 0)$. }
 - e) $E_x = E_x(y,z)$. Leads to $\vec{H} = (0, H_y, H_z)$. }
 - f) $E_x = E_x(x,y,z)$. " " " " }
- No seeming contradiction. (so far)

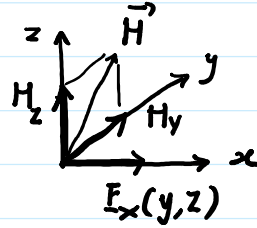
- 5) To further narrow the possibilities, consider the eqn:
 $\nabla \times \vec{H} = j\omega \epsilon_0 \vec{E}$ for the cases (c,d,e,f) above,
 ie. for $\vec{H} = (0, H_y, H_z)$.
- | | | |
|-------------------------------|-------------------------------|-------------------------------|
| \hat{x} | \hat{y} | \hat{z} |
| $\frac{\partial}{\partial x}$ | $\frac{\partial}{\partial y}$ | $\frac{\partial}{\partial z}$ |
| 0 | H_y | H_z |
- $$\nabla \times \vec{H} = \begin{pmatrix} \frac{\partial H_z}{\partial y} - \frac{\partial H_y}{\partial z}, \frac{\partial H_z}{\partial x}, \frac{\partial H_y}{\partial x} \end{pmatrix} = j\omega \epsilon_0 (E_x, 0, 0)$$
- Must be consistent
- \Rightarrow Both $\frac{\partial H_z}{\partial x} = 0$ and $\frac{\partial H_y}{\partial x} = 0$ and so \vec{H} is only a fn of (y,z) NOT x .
obsv #2

- 6) Going back to eqn (1), we get: $H_y(y,z) = \frac{j}{\omega \mu} \frac{\partial E_x}{\partial z}$ and
 $H_z(y,z) = \frac{-j}{\omega \mu} \frac{\partial E_x}{\partial y}$

Since the LHS are only fns of (y,z) , RHS must also be so

Since the LHS are only fns of (y, z) , RHS must also be so
 $\Rightarrow E_x = E_x(y, z)$
 Thus possibility (f) in point (4) is invalid. obsv #3.

7) The fields we have now are:



Thus even in the most general case
 \vec{E} and \vec{H} are perpendicular. \leftarrow obsv #4

8) In this general setting we can make life even easier by aligning our coordinate axis in such a way that \vec{E} is along \hat{x} and \vec{H} along \hat{y} . Our choice!
 So $\vec{E} = (E_x, 0, 0)$ and $\vec{H} = (0, H_y, 0)$.

9) Above $\Rightarrow H_z = 0$. From eqn (1) we then get $H_z \propto \frac{\partial E_x}{\partial y} = 0$
 This suggests E_x is not a fn of y , only z .
 So we have narrowed it down to case (d) from pt (4).
 The same eqn gave $H_y \propto \frac{\partial E_x}{\partial z} \Rightarrow H_y$ is only a fn of z .

10) Conclusion: Even the most general situation can be written as $\vec{E} = (E_x(z), 0, 0)$ and $\vec{H} = (0, H_y(z), 0)$ by convenient choice of coordinate system.