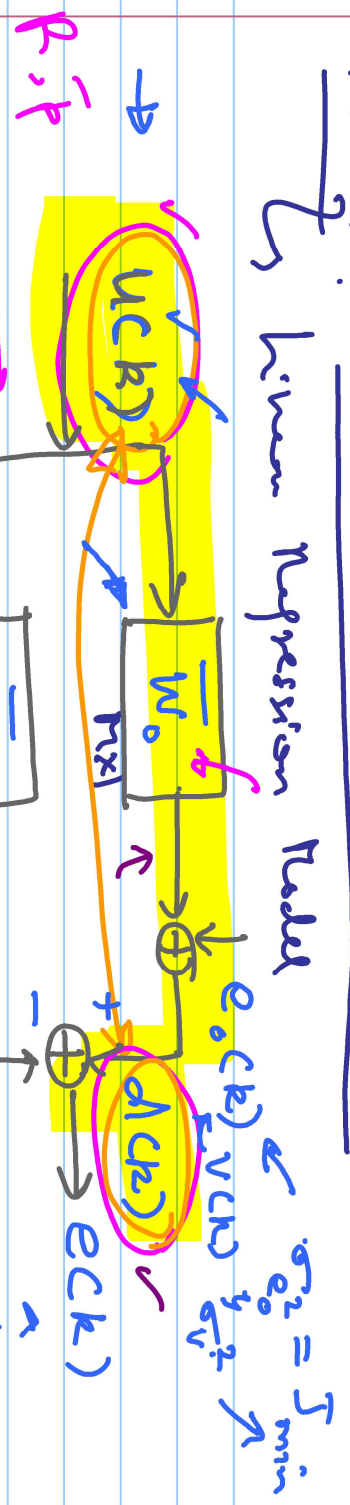


Result: Linear Regression Model →



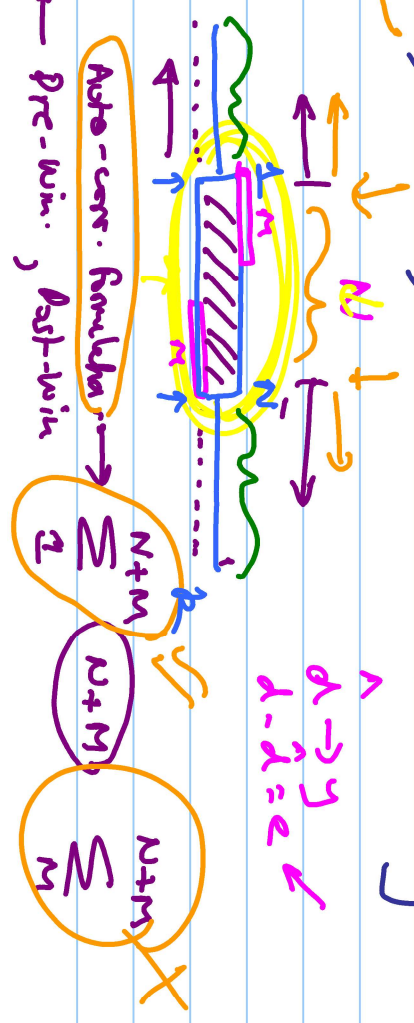
$W_0 \rightarrow ??$

LS Criterion

Given  $\{u(1), u(2), u(3), \dots, u(M), u(N), u(N-1), u(N)\}$

$$\min_{W_{M \times 1}} \sum_{i=1}^N |e(i)|^2$$

Covariance formulation  $\sum_{i=1}^N$



Auto-corr. Formula, Pre-win., Post-win.

$$\sum_{i=1}^{N+M}$$

Matrix-vector notation

LS  $\rightarrow$  RLS  $\rightarrow$  KF

Define:

$$A^H \begin{matrix} \xrightarrow{m} \\ \xrightarrow{m} \end{matrix} \begin{matrix} \xrightarrow{m} \\ \xrightarrow{m} \end{matrix}$$

$$\begin{bmatrix} | & | & | \\ \bar{u}(m) & \bar{u}(m+1) & \dots & \bar{u}(N) \\ | & | & | \end{bmatrix}; \quad A = \begin{bmatrix} -\bar{u}^*(m) & - \\ -\bar{u}^*(m+1) & - \\ \vdots & \vdots \\ -\bar{u}^*(N) & - \end{bmatrix}$$

$$\bar{d}^H = \left[ \underbrace{d(m)}_{\xrightarrow{n-m+1}} \quad \underbrace{d(m+1)}_{\xrightarrow{n-m+1}} \quad \dots \quad \underbrace{d(N)}_{\xrightarrow{n-m+1}} \right]; \quad \bar{d} = \begin{bmatrix} d^*(m) \\ \vdots \\ d^*(N) \end{bmatrix}; \quad \bar{d} = \begin{bmatrix} \bar{d} \\ \bar{d} \\ \vdots \\ \bar{d} \end{bmatrix}; \quad \bar{d} = \begin{bmatrix} \bar{d} \\ \bar{d} \\ \vdots \\ \bar{d} \end{bmatrix}$$

$$\sum_{i=m}^N |e(i)|^2$$

Exercise: Show that this leads to

$$\frac{d}{ds} (z(i)) = 0$$

$$\bar{\Phi} \bar{w} = \bar{z}$$

Recall: Wiener Eq.  $R \bar{w} = \bar{p}$

$$\text{where } \bar{\Phi} = A^H A; \quad \bar{z} = A \bar{d}; \quad \bar{w}_{LS} = \bar{\Phi}^{-1} \bar{z}$$

$$\bar{w}_{LS} = \bar{Q}^{-1} \bar{z} = (A^H A)^{-1} A^H \bar{z}$$

"A" is "perp"
Moore-Penrose Pseudo Inverse

(\*) Principle of orthogonality (in LS)

$$e(k) = d(k) - \hat{d}(k)$$

$$\rightarrow \sum_{k=M}^N y(k) e^*(k) = 0$$

$$\rightarrow d(k) = \hat{d}(k) - y(k)$$

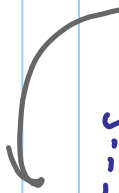
$$\Rightarrow d(k) = e(k) + y(k)$$

$\bar{d}$

$$\bar{d} = \bar{e} + \bar{y}$$

$$\bar{Q} \bar{w} = \bar{z}$$

show that



orth

$$\bar{y} = A \bar{w}$$

$$\bar{y}^H = \bar{w}^H A^H$$

$$\bar{y}^H \bar{y} = \bar{w}^H A^H A \bar{w}$$



$$= \bar{w}^H \bar{z}$$

$$\begin{aligned}
 \hat{\Sigma}_{mi} &= \hat{\Sigma}_d - \hat{\Sigma}_{out} = \hat{d}^H \hat{d} - \hat{w}_u^H \Phi \hat{w}_u \\
 &= \hat{d}^H \hat{d} - \hat{w}_u^H \hat{z}
 \end{aligned}$$

$\hat{\Sigma}_{mi} = \hat{\sigma}_d^2 - \hat{w}_u^H R_u \hat{w}_u$   
 $= \hat{\sigma}_d^2 - \hat{w}_u^H \hat{p}$

## Properties of the LS Estimate

(1)  $\hat{d} = A \hat{w}_0 + e_0(n)$ , if  $e_0(n)$  is zero mean  $\Rightarrow$

Proof:  $\hat{w}_{LS} = (A^H A)^{-1} A^H \hat{d} = \hat{w}_0 + (A^H A)^{-1} A^H e_0(n)$

$\hat{w}_{LS}$  is unbiased  $\Rightarrow$   
 $E[\hat{w}_{LS}] = \hat{w}_0$

(2) If  $e_{0(n)}$  is zero-mean & white, with variance  $\sigma^2$

Then  $\text{Cov}(\bar{w}_{LS}) \stackrel{?}{=} E[(\bar{w}_{LS} - \bar{w}_0)(\bar{w}_{LS} - \bar{w}_0)^H] = \sigma^2 \Phi^{-1}$

↙ BLUE ↘

(3) If  $e_{0(n)}$  is zero-mean, white, & Gaussian, then (efficient)

$\bar{w}_{LS}$  achieves the Cramer-Rao LB for unbiased estimators.

$$E[(\bar{w}_{LS} - \bar{w}_0)(\bar{w}_{LS} - \bar{w}_0)^H] \geq J^{-1}$$

where  $J$  is the Fisher information matrix

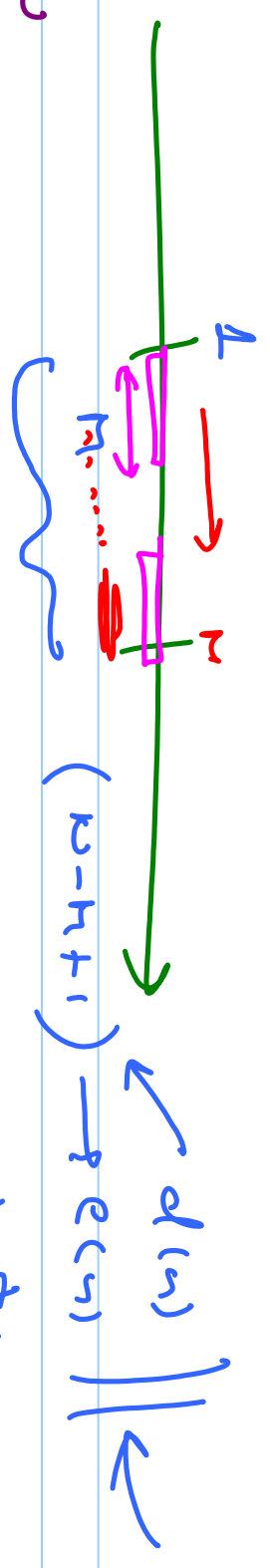
↙ BLUE ↘

$$J \stackrel{\Delta}{=} \int_{\text{Rxn}} \left[ \left( \frac{\partial \mathcal{L}}{\partial u_0^*} \right) \cdot \left( \frac{\partial \mathcal{L}}{\partial u_1^*} \right) \right]$$

where  $\mathcal{L} = \mathcal{L}_n f_{\bar{e}}^c(\bar{e}_0)$  where  $f_{\bar{e}}^c(\bar{e}_0) = \frac{1}{(D\sigma_2)^{n-m+1}}$

$$\text{exp} \left[ \begin{array}{c} -H \\ -\frac{1}{\sigma^2} \bar{e}_0 \end{array} \right]$$

Proof: First show that  $J = \frac{1}{\sigma^2} \Phi_{\text{Rxn}}$



$$S_y = \sum_{i=1}^n |e_i|$$

"forgetting"  
"forgetting"

$w_0 \rightarrow$  constant

$$S = \sum_{i=1}^n \lambda^{n-i} |e_i|^2 + \sum_{i=1}^n \lambda^n \|\bar{w}(e_i)\|^2$$

w-LS

regularisation term



